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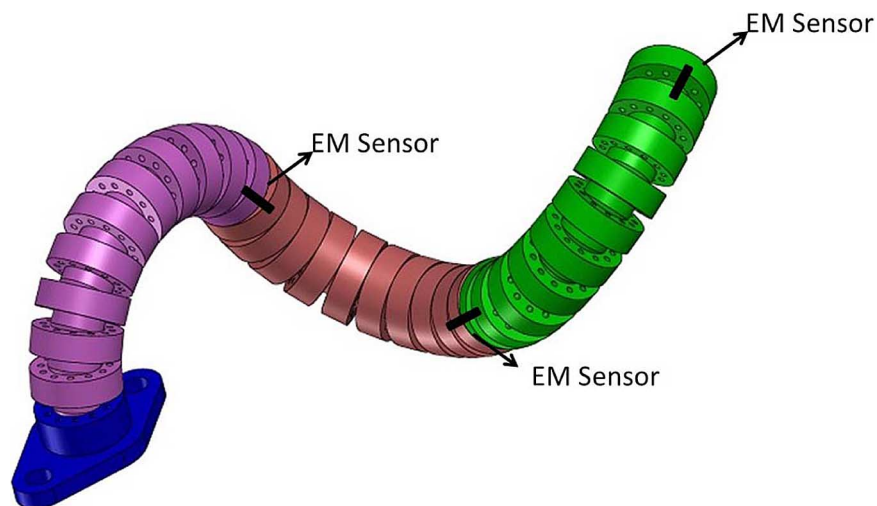
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Multisection wire-driven flexible robot shown as a backbone comprising several sections. The tip position and shape information is reconstructed with two electromagnetic sensors mounted at each section's distal end (see page 4566).